

UG10087

Asynchronous Sample Rate Converter

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User guide

Document information

Information	Content
Keywords	Asynchronous Sample Rate Converter, ASRC, UG10087
Abstract	The Asynchronous Sample Rate Converter (ASRC) software module compensates the drift between two mono audio signals. This is not a frequency converter and so the nominal signal frequency is the same before and after the ASRC.



1 Introduction

The Asynchronous Sample Rate Converter (ASRC) software module compensates the drift between two mono audio signals. This is not a frequency converter and so the nominal signal frequency is the same before and after the ASRC.

The system works asynchronously. It compensates the difference between the input and output sampling rates with different clock domains.

2 ASRC overview

The ASRC overview describes the problem and the solution.

2.1 Problem

For the use case with two different clock domains. Due to clock drift, the audio sample rates are not 100 % identical. It is a result of a data buffering error. Therefore, at a particular moment, there is either too much data or not enough data. For audio use cases, it results of an audio artifact.

Example:

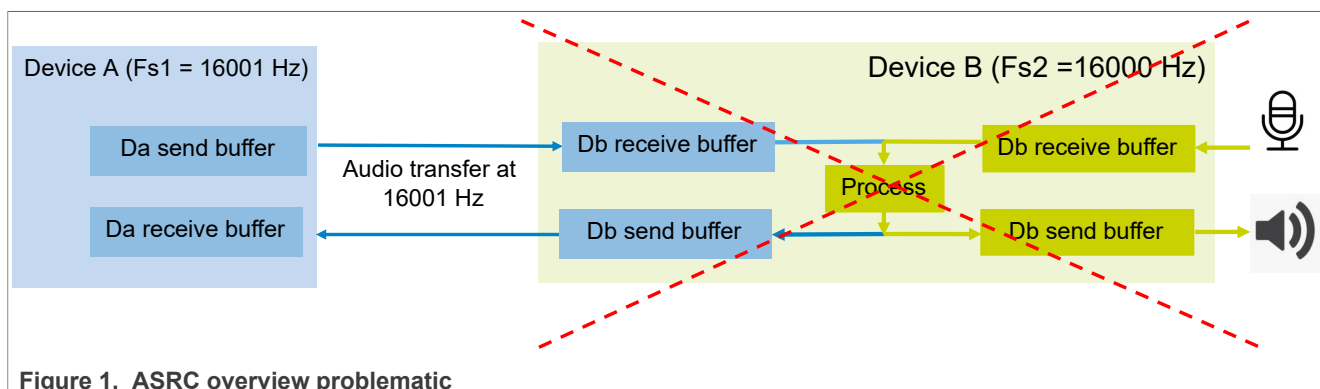


Figure 1. ASRC overview problematic

- Audio samples captured at $f_{s1} = 16001$ Hz by device B due to audio link transfer
- The device B consumed the audio sample at $f_{s2} = 16000$ Hz

At a moment:

- There are too many samples in the device B receive buffer.
- There are no more samples in the device B send buffer.
- It generates an audio artifact.

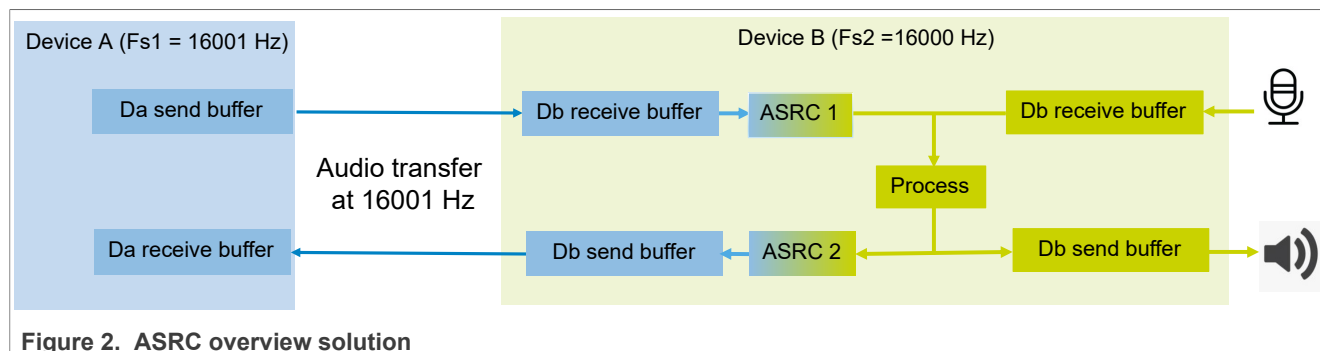
2.2 Solution

The solution is to use an ASRC) block to estimate the sample rate ratio and correct it. The block helps adjust the number of audio data consumed and generated by the device.

Example:

The ASRC block estimates the **sample rate ratio** ($\gamma = \frac{f_{s1}}{f_{s2}}$) between frequency 1 and frequency 2.

It helps adjust the number of audio data consumed and generated by the device B process and adjust it to its own frequency.



3 Application programmer interface (API)

All public structure, function, and definition are available in the **ASRC.h** header file.

3.1 ASRC enums and structures

This topic lists the following ASRC enums and structures.

- [Section 3.1.1 "ASRC_LibInfo_st"](#)
- [Section 3.1.2 "ASRC_ReturnStatus_en"](#)
- [Section 3.1.3 "ASRC_OperatingMode_en"](#)
- [Section 3.1.4 "ASRC_Fs_en"](#)
- [Section 3.1.5 "ASRC_InstanceParams_st"](#)
- [Section 3.1.6 "ASRC_ControlParams_st"](#)

3.1.1 ASRC_LibInfo_st

```
/* ASRC_Lib_Info_st structure */
typedef struct
{
    PL_UINT8          ASRC_LIB_Release_MAJOR;
    PL_UINT8          ASRC_LIB_Release_MEDIUM;
    PL_UINT8          ASRC_LIB_Release_MINOR;

} ASRC_LibInfo_st;
```

Figure 3. ASRC library version

3.1.2 ASRC_ReturnStatus_en

```
// Error type
typedef enum
{
    ASRC_SUCCESS,                /// Successful return from a routine
    /// invalid silicon
    ASRC_INVALID_SILICON_CHECK,  /// NXP board check not valid
    /// invalid parameters
    ASRC_INVALID_BUFFER_MEMORY_ALIGNMENT, /// Memory alignment error
    ASRC_INVALID_NULL_ADDRESS,    /// Memory alignment error
    /// Error in given ASRC_InstanceParams_st
    ASRC_INVALID_INPUT_FRAME_SIZE, /// InputSamplesPerFrame parameter not supported
    ASRC_INVALID_OUTPUT_FRAME_SIZE, /// OutputSamplesPerFrame parameter not supported
    ASRC_INVALID_FRAME_SIZE,
    ASRC_INVALID_TARGET_FREQUENCY, /// targetFs not supported
    ASRC_INVALID_PI_CONTROLLER_ON, /// PIControllerON parameter is not boolean value
    ASRC_INVALID_ASRC_ENABLE,     /// ASRC_Enable parameter is not boolean value
    ASRC_INVALID_ALPHA,          /// alpha parameter not supported
    ASRC_INVALID_BETA,           /// beta parameter not supported
    ASRC_INVALID_LAMBDA,         /// lambda parameter not supported
    ASRC_INVALID_OPERATING_MODE,  /// OperatingMode parameter not supported
    ASRC_INVALID_SYSTEM_CLOCK,    /// systemClock parameter not supported
    /// circular buffer error cases
    ASRC_CIRCULAR_BUFFER_OVERFLOW, /// read and write pointer equals
    ASRC_CIRCULAR_BUFFER_FULL,     /// not space to write in circular buffer
    ASRC_CIRCULAR_BUFFER_EMPTY,    /// not enough data to read in circular buffer
    ASRC_CIRCULAR_BUFFER_ERROR,
    /// general errors
    ASRC_ERROR_UNDEFINED,          /// undefined error
    ASRC_SYSTEM_ERROR,            /// Unknow error
    ASRC_NB_ERROR                  /// number of error
} ASRC_ReturnStatus_en;
```

Figure 4. ASRC error type

3.1.3 ASRC_OperatingMode_en

Helps select between the two modes:

- **Master:** ASRC computes the ratio based on input and output ASRC internal circular buffer level
- **Slave:** ASRC used a given external ratio

```

/* ASRC Operating Mode
*/
typedef enum
{
    ASRC_DISABLE           ,          /// module deactivated
    ASRC_MASTER_MODE       ,          /// evaluate and fix gamma value within ASRC
    ASRC_SLAVE_MODE        ,          /// user fix gamma value
    ASRC_NUMBER_OF_OPERATING_MODE

} ASRC_OperatingMode_en;

```

Figure 5. ASRC operating mode

3.1.4 ASRC_Fs_en

The list of supported frequency sample rate. The current library was tested only for Fs equal to 16,000 Hz. To support different sample rates, contact the NXP support.

```

typedef enum
{
    ASRC_FS_16000 = 0 , // 16kHz sampling rate
    ASRC_FS_INVALID

} ASRC_Fs_en;

```

Figure 6. Frequency sample rate

3.1.5 ASRC_InstanceParams_st

```

typedef struct
{
    ASRC_OperatingMode_en  OperatingMode;          /// see enum
    PL_UINT16              InputSamplesPerFrame;    /// [ 41 - 120 ]    Number of input samples per frame
    PL_UINT16              OutputSamplesPerFrame;   /// [ 41 - 120 ]    Number of output samples per frame
    ASRC_Fs_en             targetFs;                /// { 16000 }        Estimate frequency of input and output
    PL_UINT32              systemClock;             /// [ 50MHz - 2GHz ] System Platform clock rate

} ASRC_InstanceParams_st;

```

Figure 7. Used to create an ASRC instance.

3.1.6 ASRC_ControlParams_st

```

/* Control Parameter structure */
typedef struct
{
    PL_BOOL      PIControllerON; /// { true, false } Enable analysis part of ASRC
    PL_BOOL      ASRC_Enable;    /// { true, false } Enable ASRC PIController and synthesis : if false ASRC is transparent

    PL_FLOAT      alpha_copy;    /// [ -0.01 - 0.01] Copy of the Proportional gain of the PI Controller
                                /// Default : -0.00015, if increased, faster convergence but larger oscillation

    PL_FLOAT      beta_copy;     /// [ -0.01 - 0.01] Copy of the Integral gain of the PI Controller
                                /// Default : -0.00000005, if increased, the history get more importance in the calculation but can cause overshoot

    PL_FLOAT      lambda_copy;   /// [ 0 - 1] Copy of the smoothing of parameter for AOD_corrected computation
                                /// Default : 0.08, if increased, faster convergence but larger oscillation
} ASRC_ControlParams_st;

```

Figure 8. Used to control the ASRC instance

Default value: optimum configuration for 10 Hz drift:

- $\lambda = 0.08$
- $\alpha = -0.00015$
- $\beta = -0.00000005$

See code comments for tuning the controller parameters.

3.2 Functions

This topic lists the following ASRC functions.

- [Section 3.2.1 "ASRC_GetLibInfo"](#)
- [Section 3.2.2 "ASRC_GetMemoryTable"](#)
- [Section 3.2.3 "ASRC_GetInstanceHandle"](#)
- [Section 3.2.4 "ASRC_SetControlParameters"](#)
- [Section 3.2.5 "ASRC_GetRatio"](#)
- [Section 3.2.6 "ASRC_GetControlParameters"](#)
- [Section 3.2.7 "ASRC_Push"](#)
- [Section 3.2.8 "ASRC_Pull"](#)
- [Section 3.2.9 "ASRC_Process"](#)

3.2.1 ASRC_GetLibInfo

```

/**
 * @brief
 *
 * @param pLib_Info
 * @return ASRC_ReturnStatus_en
 */
ASRC_ReturnStatus_en ASRC_GetLibInfo(ASRC_LibInfo_st *pLib_Info);

```

Figure 9. Get the ASRC library information

3.2.2 ASRC_GetMemoryTable

Get the amount of memory required by the ASRC library.

```

/**
 * @brief
 *
 * @param hInstance
 * @param pMemoryTable
 * @param pInstanceParams
 * @return ASRC_ReturnStatus_en
 */
ASRC_ReturnStatus_en ASRC_GetMemoryTable(ASRC_Handle_t      hInstance,
                                         PL_MemoryTable_st  *pMemoryTable,
                                         ASRC_InstanceParams_st *pInstanceParams);

```

Figure 10. Get the amount of memory required

3.2.3 ASRC_GetInstanceHandle

```

/**
 * @brief
 *
 * @param phInstance
 * @param pMemoryTable
 * @param pInstanceParams
 * @return ASRC_ReturnStatus_en
 */
ASRC_ReturnStatus_en ASRC_GetInstanceHandle( ASRC_Handle_t      *phInstance,
                                             PL_MemoryTable_st  *pMemoryTable,
                                             ASRC_InstanceParams_st *pInstanceParams);
...

```

Figure 11. Create an ASRC library instance

3.2.4 ASRC_SetControlParameters

Set the ASRC control parameters. It is used to update the control parameter after an ASRC instance is created. It can be used when the use case is running.

```

/**
 * @brief
 *
 * @param phInstance
 * @param pNewParams
 * @return ASRC_ReturnStatus_en
 */
ASRC_ReturnStatus_en ASRC_SetControlParameters( ASRC_Handle_t      phInstance,
                                                ASRC_ControlParams_st *const pNewParams);

```

Figure 12. Set the ASRC control parameters

3.2.5 ASRC_GetRatio

```
/**
 * @brief
 *
 * @param asrcHandler
 * @param gamma
 * @return ASRC_ReturnStatus_en
 */
ASRC_ReturnStatus_en ASRC_GetRatio(ASRC_Handle_t asrcHandler,
                                   PL_FLOAT *gamma);
```

Figure 13. Get the current ASRC sampling rate frequency ratio

3.2.6 ASRC_GetControlParameters

```
/**
 * @brief
 *
 * @param phInstance
 * @param pControlParams
 * @return ASRC_ReturnStatus_en
 */
ASRC_ReturnStatus_en ASRC_GetControlParameters( ASRC_Handle_t      phInstance,
                                                ASRC_ControlParams_st *pControlParams);
```

Figure 14. Read the current ASRC control parameters

3.2.7 ASRC_Push

It helps add a frame to the ASRC instance for further process. This frame is at the initial sample rate.

```
/**
 * @brief push input frame
 *
 * @param asrcHandler
 * @param inputFrame
 * @return ASRC_ReturnStatus_en
 */
ASRC_ReturnStatus_en ASRC_Push(ASRC_Handle_t asrcHandler,
                               const PL_FLOAT *inputFrame);
```

Figure 15. Add a frame to the ASRC instance

3.2.8 ASRC_Pull

It helps read a frame for the ASRC instance. This frame is at the final sample rate. Final sample rate = Initial sample rate \cdot ratio.


```
/**
 * @brief
 *
 * @param asrcHandler
 * @param outputFrame
 * @param framesize
 * @param timestamp
 * @return ASRC_ReturnStatus_en
 */
ASRC_ReturnStatus_en ASRC_Pull(ASRC_Handle_t asrcHandler,
                               const PL_FLOAT *outputFrame,
                               PL_UINT16 framesize,
                               PL_UINT32 timestamp);           // according to systemClock
```

Figure 16. Read a frame for the ASRC instance

3.2.9 ASRC_Process

It launches the ASRC instance process. The ASRC process consumes a frame from the ASRC input buffer and writes a frame to the ASRC output buffer. The number of samples read and write are different according to the ratio between the two frequencies. This process helps compensate a clock drift and does not help convert the sample rate (this is not SRC).

```
/**
 * @brief Interpolate output sample if delay line ready
 *
 * @param asrcHandler
 * @param timestamp
 * @param userGammaRatio
 * @return ASRC_ReturnStatus_en
 */
ASRC_ReturnStatus_en ASRC_Process(ASRC_Handle_t asrcHandler,
                                   PL_UINT32 timestamp, // according to systemClock
                                   PL_FLOAT userGammaRatio);
```

Figure 17. Launches the ASRC instance process

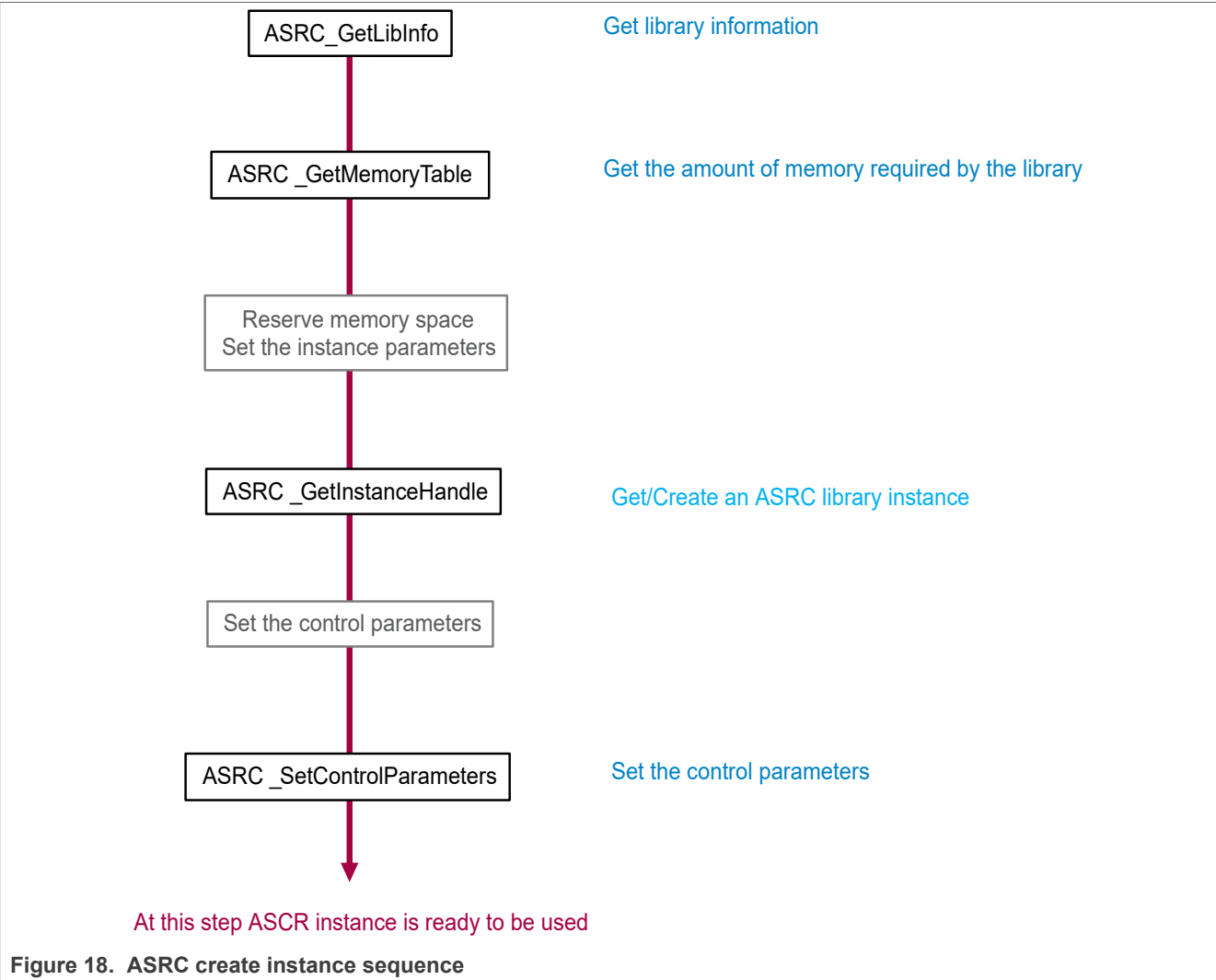
3.3 Sequence

This topic describes the [Section "Create an ASRC instance"](#) and the [Section "Run the ASRC in the process loop"](#).

3.3.1 Create an ASRC instance

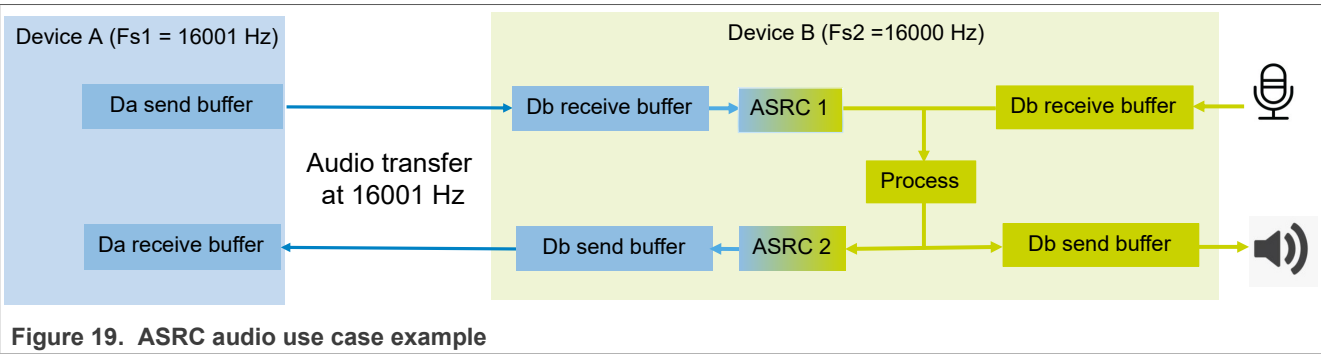
To create and configure an ASRC instance, follow the sequence in the application code.

The ASRC library does not support the grey part in [Figure 18](#). There, make sure to code the sequence in the application source code.



3.3.2 Run the ASRC in the process loop

To explain the use of ASRC, let us consider an audio flow transmission between a Device A and a Device B.



- Device A (Fs1 frequency domain) has an audio link with device B (Fs2 frequency domain). Device A is a master.
- 2 ASRC instances are required in device B:
 - ASRC1 in master mode: convert audio stream from blue to green frequency domain.

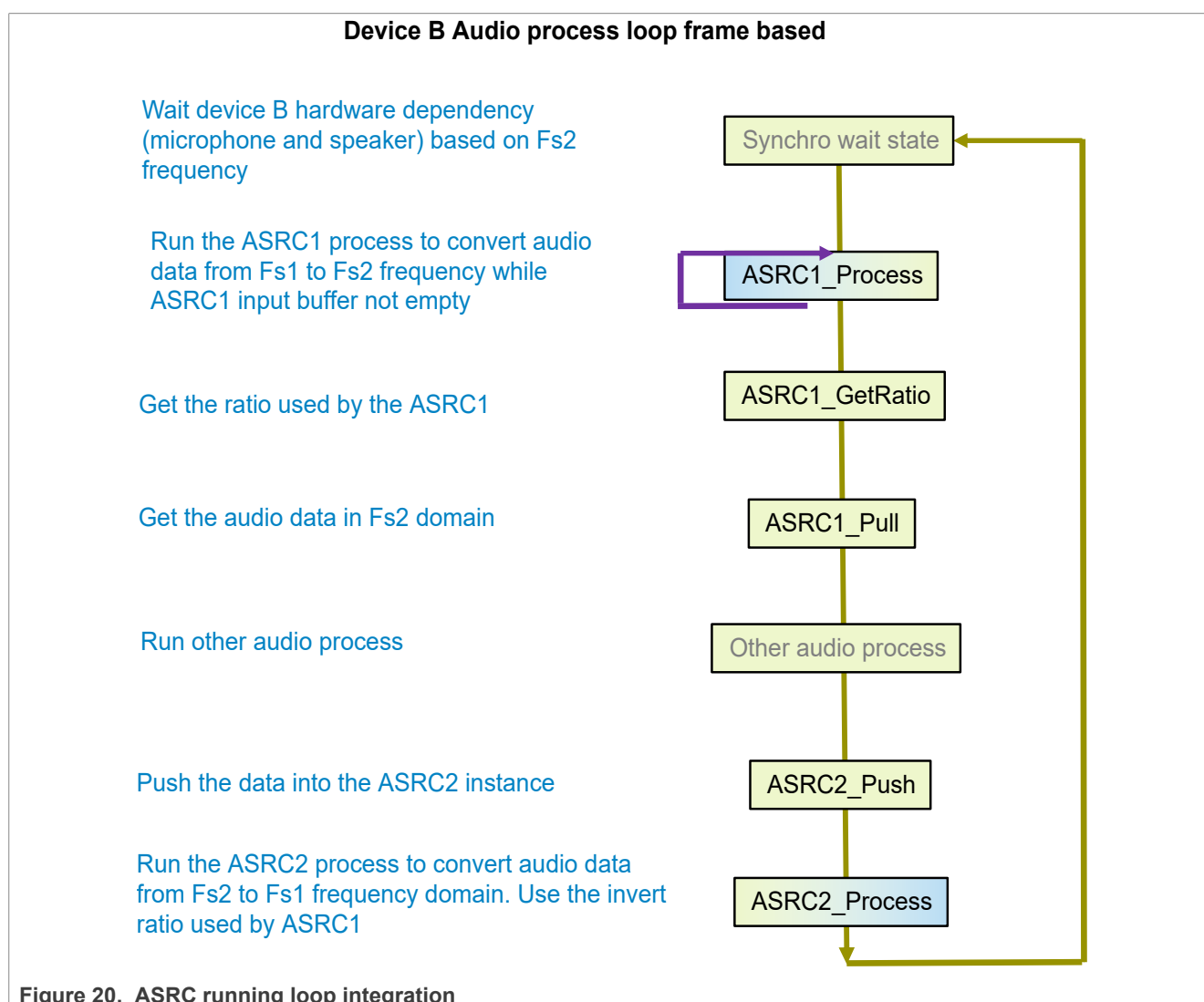
- ASRC2 in slave mode: convert audio stream from green to blue frequency domain.

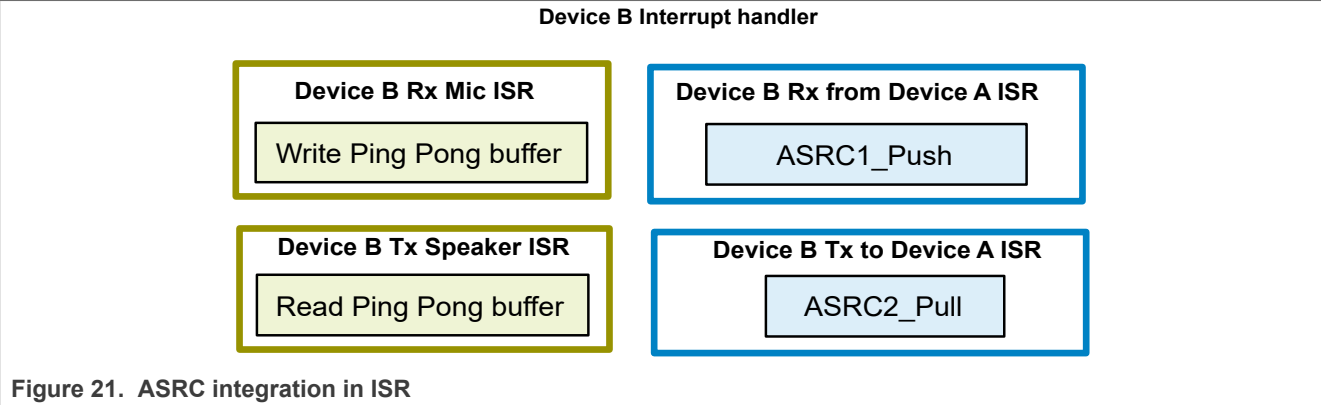
Device A does not have ASRC. It is device B, which handle the ASRCs instance.

Device B source code has got:

- Frame-based audio process loop. This loop is based on hardware dependency based on Fs2 sample rate.
- Hardware resource interrupt handler (Speaker and Microphone in our example) based on Fs2 sample rate.
- Audio transfer interrupt handler to handle hardware resource.

[Linktext-Figure_](#) schematics show how to insert the ASRC process in the loop and in the different interrupt handler.





4 Performance

This topic describes the [Section 4.1](#) and the [Section 4.2](#).

4.1 Memory consumption

4.1.1 Sample rate 16 kHz

ASRC memory can be repatriated in four different memories:

- SLOW_DATA does not impact MIPS consumption.
- FAST_DATA and FAST_COEFF must be placed in platform fast memory not to impact million instructions per second (MIPS) consumption.
- TEMPORARY_FAST must be placed in platform fast memory not to impact MIPS consumption. This amount of memory can be reused by another algorithm when the ASRC function is not under run. This can also be named scratch memory.

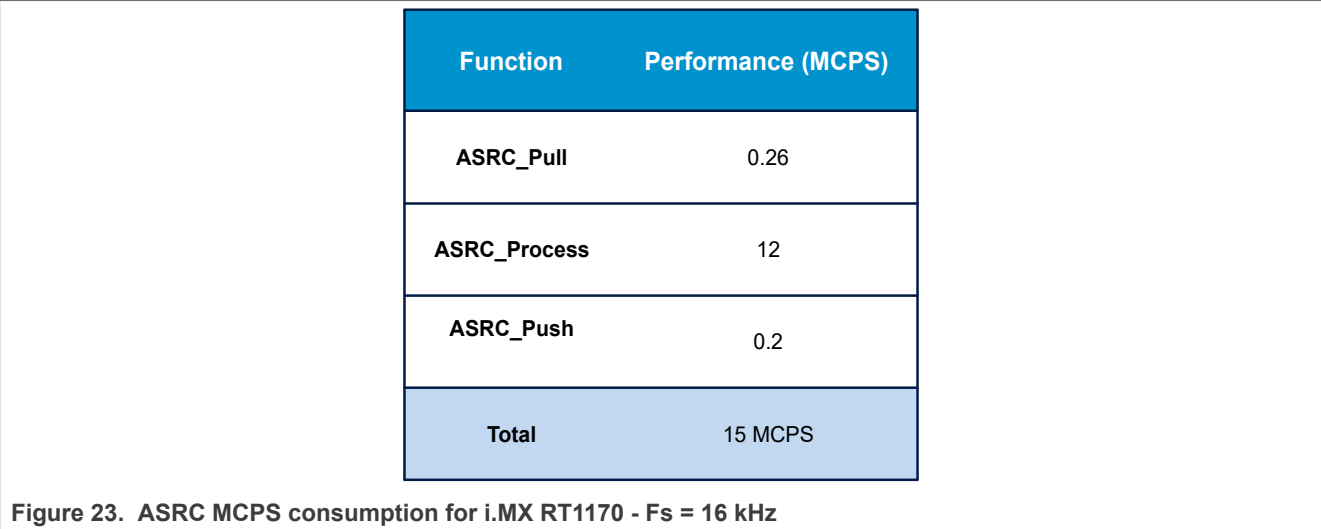
Memory type	Size (Bytes)
PL_PERSISTENT_SLOW_DATA	95
PL_PERSISTENT_FAST_DATA	2.7 K
PL_PERSISTENT_FAST_COEF	16.5 K
PL_TEMPORARY_FAST	15
TOTAL	19.4 K

Figure 22. ASRC memory consumption (Fs = 16 kHz)

4.2 MCPS consumption

4.2.1 Sample rate 16 kHz

These metrics are run on an NXP i.MX RT1170 platform. It can be slightly different according to memory access performance.



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6 Revision history

Table 1. Revision history

Document ID	Release date	Description
UG10087 v.1.0	10 January 2024	Initial version updated for MCUXpresso SDK v2.15.000.

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